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[PS] Locally Weighted Learning for Control Christopher G. Atkeson ...

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... We use cross validation to choose an appropriate distance metric and **weighting function**, ... This gives the **cost-to-go** value **function** of px ...

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... The **weighting** coefficients in the objective functions are chosen ... Richard E. **Bellman** Control Heritage Award, American Automatic Control ...

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... critic network to approximate the **cost-to-go** in the **Bellman**. equation [2] and an action network to ... the minimized value **function** or **cost-to-go**, V ...

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... **weighting function**, and to help find irrelevant input variables and terms. in the local model. ... This gives the **cost-to-go** value **function** of ...

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... the state transition rules, and the objective **function(cost-to-go)**. ... the **Bellman** Iteration gives 'converged' **cost-to-go** values rather ...

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... an optimal return or **cost-to-go function** representing the maximum return (or ... conditioned on a given initial storage state vector **Bellman's principle** ...

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... to Hamilton-Jacobi-**Bellman** equation for the problems in continuous time [3, ... terminal cost **function**: Assumption A5 The terminal **weighting** matrices Q ...

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... the evaluation **function** of policy  $\pi$ . We assume that the stochastic ... for a state is found, **Bellman's principle** of optimality allows us to infer that ...

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... (sometimes called "**cost-to-go**") **function** that are (minimally) sufficient ...  
called the "**Bellman**" equation) that the optimal value **function** has these ...  
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... Utility functions (analogous to "**cost-to-go**" functions in the control ...  
way to compute the action-value **function** is to solve the **Bellman** equations. ...  
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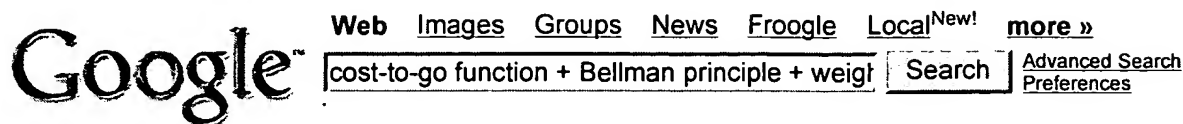
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... to **Bellman's principle** of optimality, minimization of the ... The **weighting** parameters for this **cost-to-go function** are therefore chosen ...  
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... The **weighting function** in (b) also is used for the aileron and ... learning is based on the **principle** that knowledge of the ideal **cost-to-go** ...  
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... the min-**cost-to-go** from  $x(t+1)$ ). dynamic programming (DP) **principle**: ... optimal  $u$  is a linear **function** of the state (called linear state feedback) ...  
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... and proceeding by minimizing the **cost-to-go function** step by step towards the initial node, ... using **Bellman's principle** of optimality: ...  
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... The DP technique is based on **Bellman's Principle** of Optimality, ...  $J_k^*$  ( $x(k)$ ) is the optimal **cost-to-go function** or optimal value **function** at state ...  
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... These observations lead to **Bellman's Principle** of Optimality. ... **function** is can be unbounded as long as it is  $O(u)$ , where  $u$  is a **weighting function**. ...  
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... DP technique is based on **Bellman's Principle** of Optimality, ... is the optimal **cost-to-go function** or optimal. value **function** at state ...

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... Together they generate the data **Scheduling State** Space. ... extra level of dependencies that needs to be considered when **scheduling** human **resources**. ...

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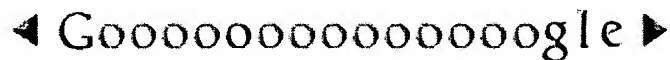
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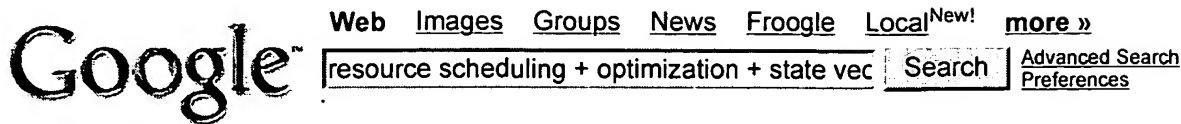
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... underlies a **scheduling optimization** level, which, in turn, suggests the best operating points (production ... is the **state vector** ...  
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... **Resource Scheduler** Controller Source **Resource Scheduler** Controller ... Here,  $x$  is the **state vector**,  $u$  the input allocation and  $i$  the index of the ...  
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... Channel **state vector**:  $S(t) = (S_1(t), S_2(t), \dots, S_L(t))$ . GS = GASA ... (3) **Resource Allocation**: Observe channel **states**  $S(t)$ . Allocate ...  
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... formulate the **optimization** problem of finding the **scheduling**/RA policy that maximizes ... base is treated as the **state vector** s in equation (13) ...  
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